

# 8. Vorlesung

12. Mrz. 2021

**Frage:** Sei  $\alpha$  stetig auf  $C^1$ ,

und sei  $\varphi_i : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$  stetig.

**Zeigt**  $\int_{\Omega} \alpha(\varphi_i) \varphi_i \, dx \rightarrow \int_{\Omega} \alpha(x) x \, dx$ .

**Denn:**

$$\int_{\Omega} \alpha(\varphi_i) \varphi_i \, dx = \int_{\Omega} \sum_{k=1}^s \alpha(\varphi_i(x)) x_k \, dx = \sum_{k=1}^s \int_{\Omega} \alpha(\varphi_i(x)) x_k \, dx$$

wobei  $\varphi_i : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$ ,  
 $[x_k] \subset \Omega$

(Idee)

$$f : \Omega \rightarrow \mathbb{R}$$

**Ist**  $\varphi_i$   $C^1$ -Funktion:  $f$  ist stetig diff.,

**Gut**

$$\begin{aligned} \partial_h f(x) &= \int_0^1 \sum_{k=1}^s \partial_h (\varphi_i(x) x_k) \, dx \\ &= \int_0^1 (\varphi_i(x) + \sum_{k=1}^s \partial_h \varphi_i(x) x_k) \, dx \\ &= \varphi_i(x) \quad (\text{B.}) \end{aligned}$$

Deriv

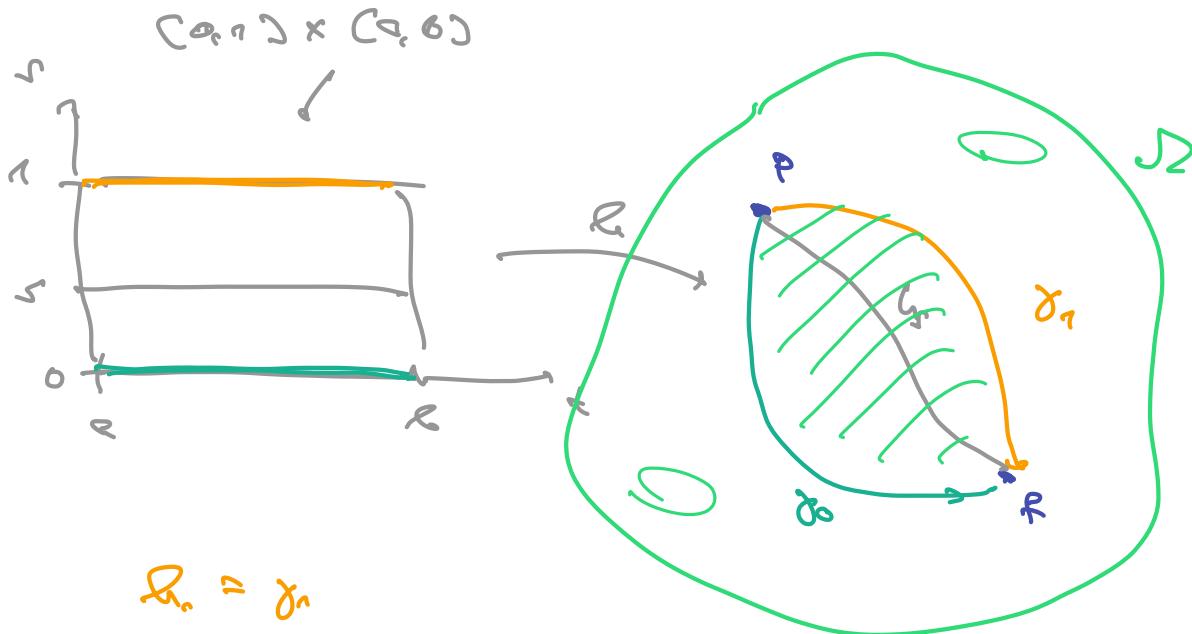
$$f_n(x) + \sum_{k=1}^n \partial_x \partial_k f_n(x) x_k \\ = \partial_x (f_n(x))$$

$$\begin{aligned} &= \partial_x (f_n(x)) \\ &= f_n(x) \quad \text{if } x_0 = 0, \\ &= \partial_n f_{x_1}. \end{aligned}$$

The first:

$$\partial_x \neq 0.$$

100



$$\delta_0 = \gamma_0$$

$$\delta_1 = \gamma_1$$

$$g_0(\gamma_1) = p, \quad g_0(\gamma_1) = p.$$

$$\mathcal{L}((0,1) \times (2,3)) \subset \mathcal{R}.$$

Bsp:

$$\gamma_0, \gamma_1 : \{a, b\} \rightarrow \mathbb{R}$$

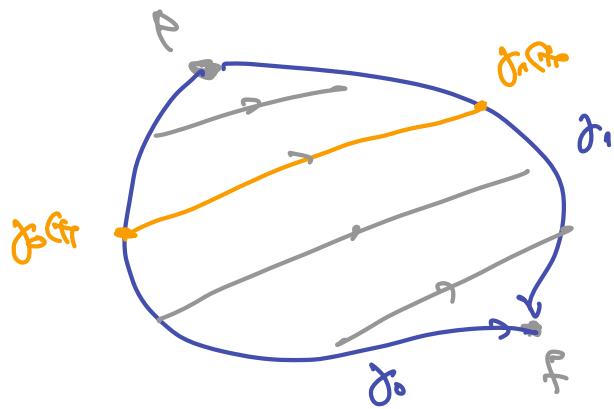
$$\left\{ \begin{array}{l} \gamma_0(a) = f_1(a) \\ \gamma_0(b) = f_1(b) \end{array} \right.$$

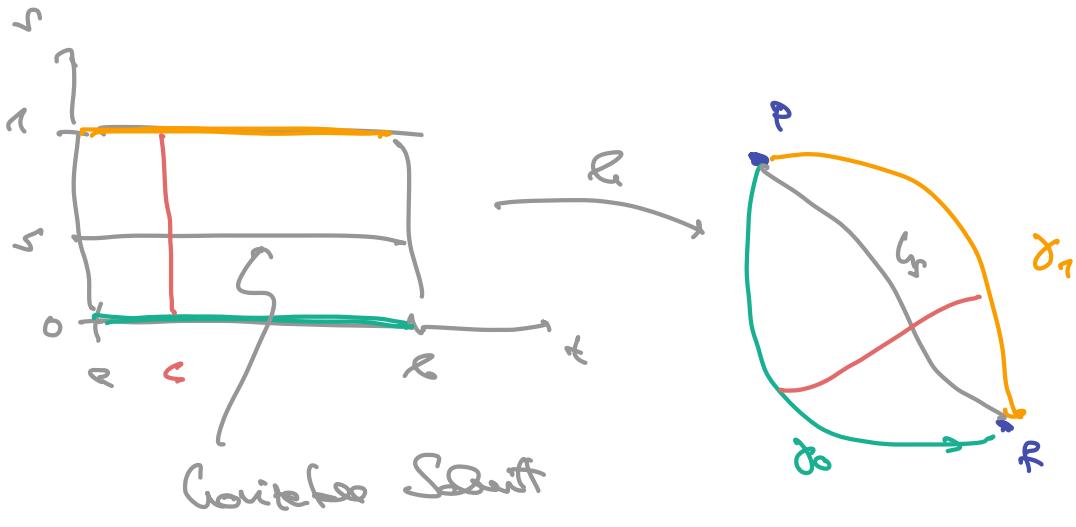
Lemma

$$[\gamma_0(t), \gamma_1(t)] \subset \mathbb{R}, \quad 0 \leq t \leq 1$$

Dann ist  $\gamma_0$  und  $\gamma_1$  homotop:

$$\lambda(s, t) := (1-s)\gamma_0(t) + s\gamma_1(t).$$





$$\{S\} \times [q, b]$$

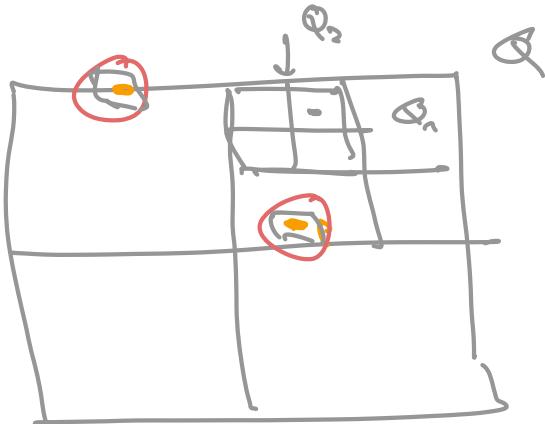
$$(a, 1) \times \{c\}$$

Zwei: Sei  $Q \subset \mathbb{C}^n \times \mathbb{C}_{\neq 0}$ ,

$\varphi: Q \rightarrow \mathbb{D}$  "funktion"

1. "Exzesse Zerlegung":

"Bogensumme, das Produkt":

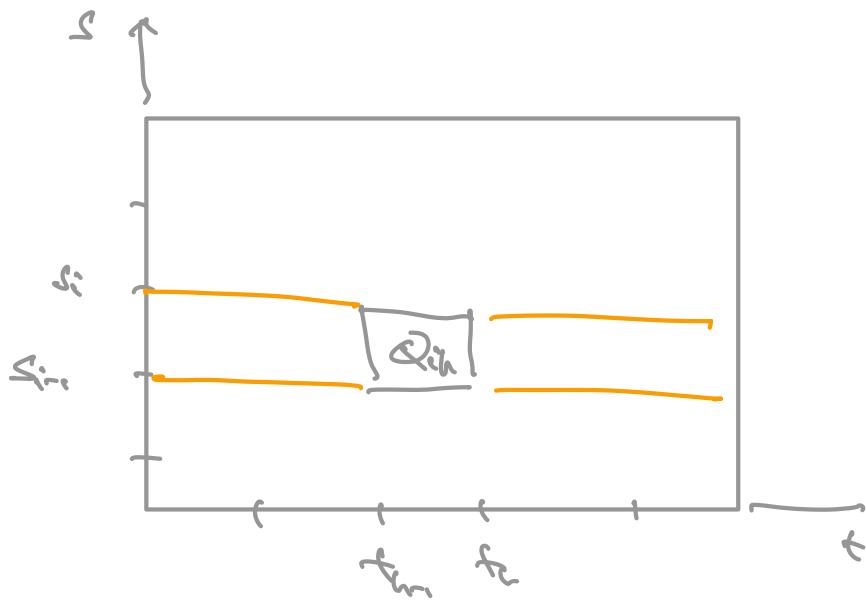


Generativ:  $\underbrace{Q \supset Q_n \supset Q_2 \supset \dots}_{\text{aus } \alpha \text{ auf } \Delta(Q_j)}$  eine Pfeil.

$$\bigcap_{n \geq 0} Q_n = \{p\} \subset \mathbb{R}$$

für alle  $p$  ist  $\alpha$  stetig.

$y$



$$Q_{i,n} = [s_{i,n}, s_i] \times [t_m, t_n],$$

$1 \leq i \leq m$   
 $1 \leq n \leq r.$

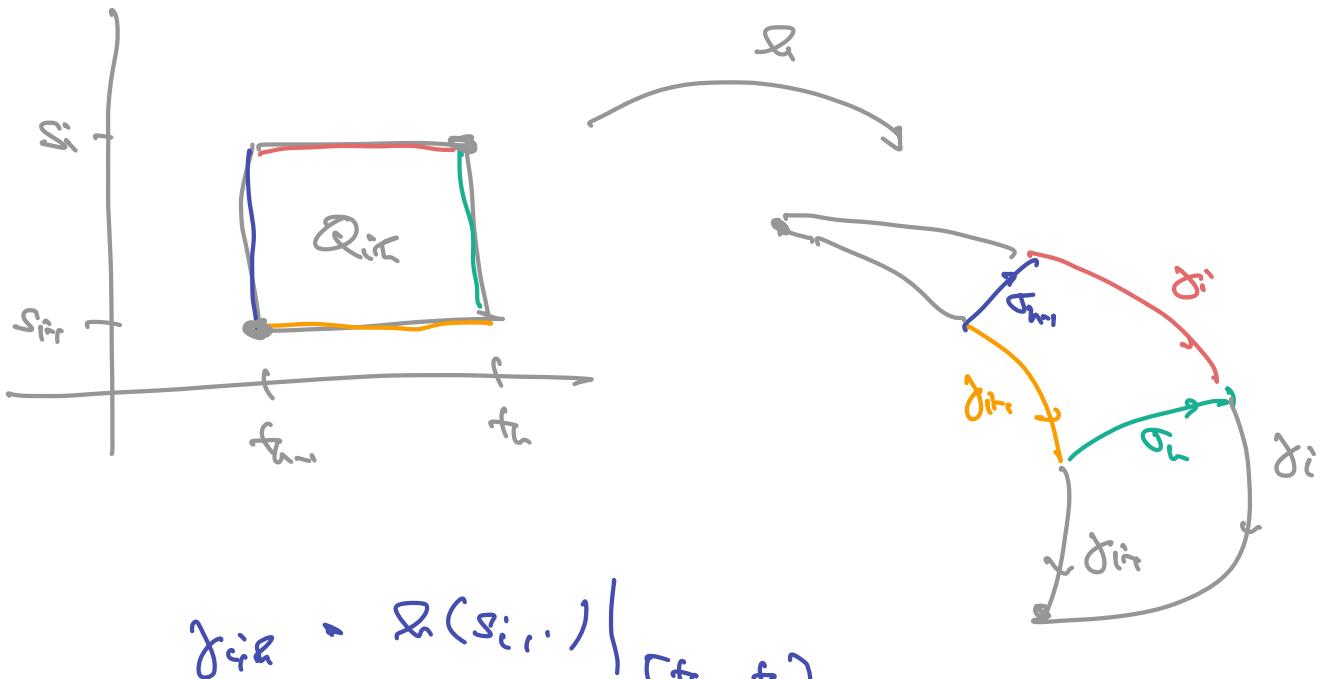
$\alpha$  in  $\alpha$  Gugby  $\alpha$   
 $Q_{i,n}$   $\alpha$ .

$$2. \text{ Zeigt: } \int_{\delta_m} \alpha = \int_{\delta_i} \alpha,$$

$$\text{wobei } \delta_i = \Delta(s_i, \cdot) = Q_{i,n}.$$

Denn

$$\int_{\delta_0} \alpha = \int_{\delta_i} \alpha.$$



$$y_{ik} = \pi(s_i, \cdot) \Big|_{[t_m, t_2]}$$

$$g_r = \Delta(\cdot, x_r) \Big|_{\{x_i, y_i\}}$$

$$\gamma_{int,R} + \sigma_R = \sigma_{ini} + \delta_{IR}$$

Dr. & Rest w/ Change in air:

$$\int_{\gamma_{i-1,R}} \alpha + \int_{\kappa} \alpha = \int_{\gamma_i} \alpha + \int_{\gamma_{i,R}} \alpha$$

Die gibt für alle Re . Seine ist die :

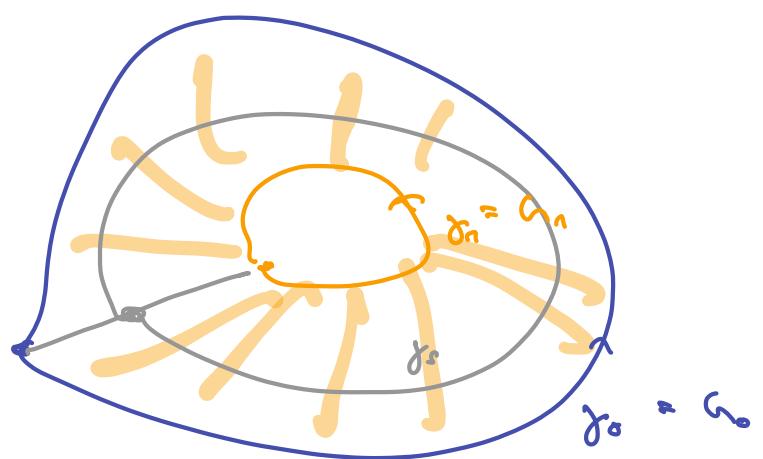
$$\int_{\gamma_{ij}} \alpha + \underbrace{\sum_{k=0}^n \int_{\gamma_k} \alpha}_{\text{boundary terms}} = \sum_{k=1}^{n+1} \int_{\gamma_k} \alpha + \int_{\gamma_i} \alpha$$

$$\Rightarrow \int_{\partial_i} \alpha + \int_{\partial_0} \alpha = \int_{\partial_i} \alpha$$

Dault-Scher

$$\Rightarrow \int_{\partial_{int}} \alpha = \int_{\partial_i} \alpha .$$

(W)



$$\mathcal{Q}: [0, \pi] \times [0, \infty) \rightarrow \mathbb{R}$$

$$\gamma_s = \mathcal{Q}(s, \cdot) = \zeta_s$$

## Basis für freie Homotopie:

Die gilt für alle  $\alpha$ . Seien  $i_1, i_2$ :

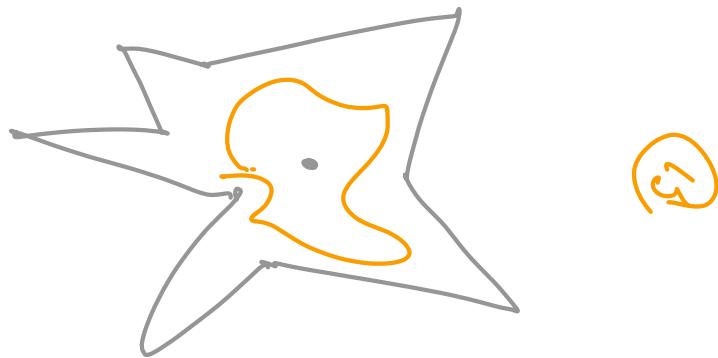
$$\int_{\gamma_{i_1}} \alpha + \sum_{k=1}^n \int_{\partial D_k} \alpha = \sum_{k=1}^n \int_{\partial D_{i_2}} \alpha + \int_{\gamma_{i_2}} \alpha$$

⇒  $\int_{\gamma_{i_1}} \alpha + \int_{\gamma_{i_2}} \alpha = \int_{\gamma_{i_1}} \alpha + \int_{\gamma_{i_2}} \alpha.$

⇒  $\int_{\gamma_{i_1}} \alpha = \int_{\gamma_i} \alpha.$  (W)

Beispiele:

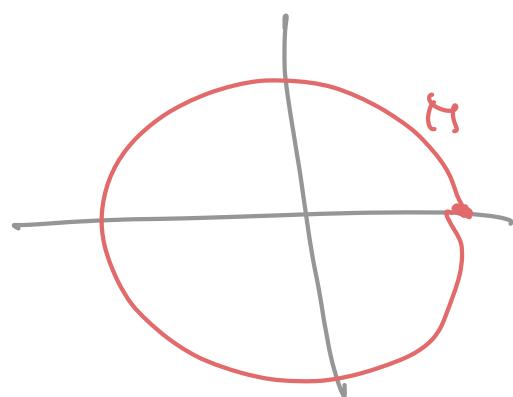
1. Steifkörper  $\Gamma$  gegeben



2.  $\Gamma = \{x \in \mathbb{R}^n : \|x\| = 1\}$

rechteckige Form von  $\Gamma$ .

$\Gamma$  rein reell:

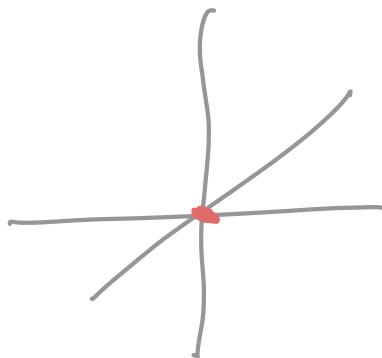


$\Gamma$  reell:



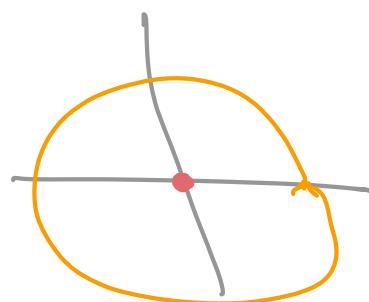
w

$$\mathcal{R}_w \setminus \{z_0\}$$



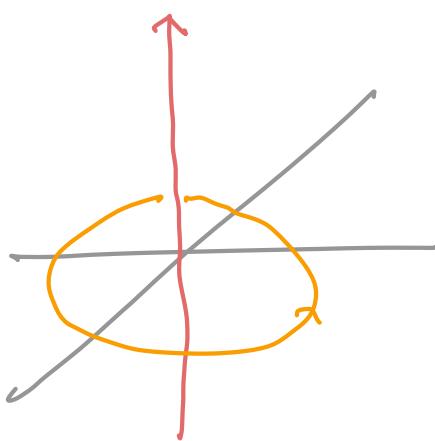
f.  $\mathcal{R}^2 \setminus \{z_0\}$

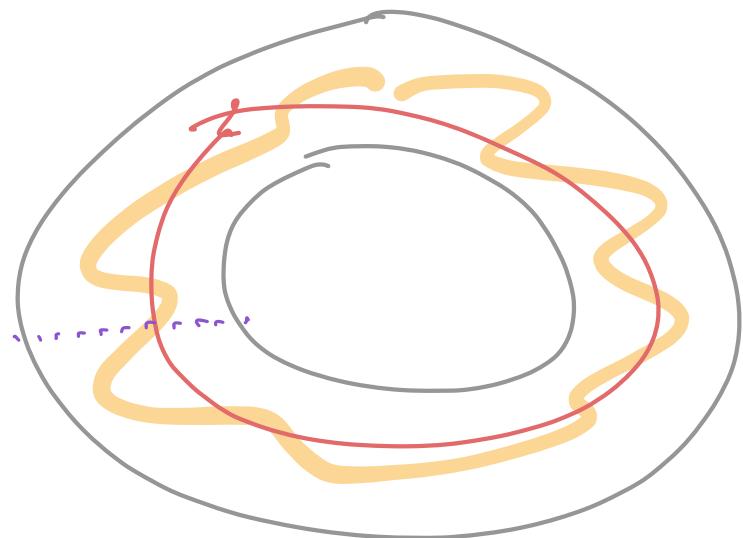
niche  $\rightarrow$  2D.



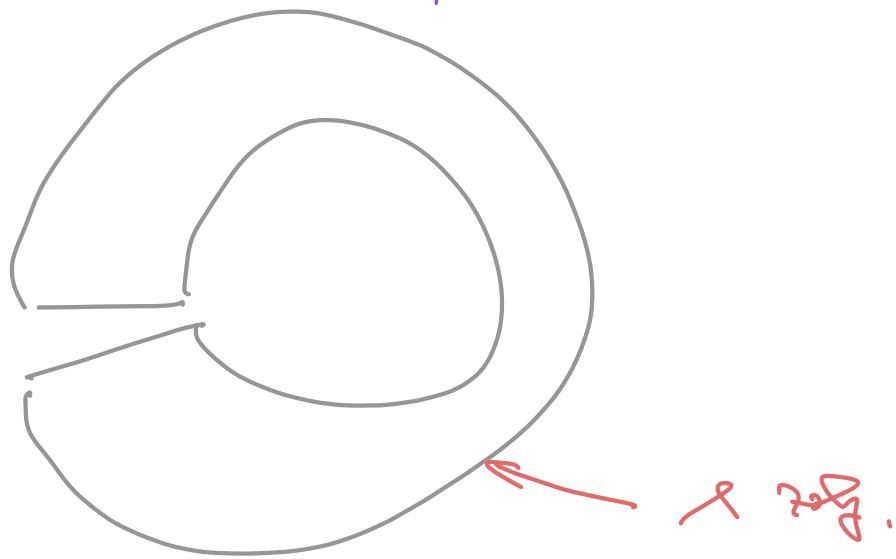
5.

$$\mathcal{R}_w \setminus \text{Gauß}$$





nicht 1-teilig



Frage:

$\mathcal{D} \times U \rightarrow_0$  "Rotation  $O"$

$\rightarrow \alpha_v = \langle v, \cdot \rangle$  für alle

$\Rightarrow \alpha_v$  global exist

Gebt manche z.B.:

$\Rightarrow \alpha_v$  global exist:

$$\alpha_v = \langle v, \cdot \rangle$$

Wanted:  $v = Du$ . 

